

## SYSTEM FOR RESISTING LIMB MOVEMENT

**Publication number:** US5201772 (A)

**Publication date:** 1993-04-13

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**Classification:**

**- international:** A61F5/01; A61H1/02; B25J9/16; B25J13/08; B25J19/00;  
A61F5/01; A61H1/02; B25J9/16; B25J13/08; B25J19/00;  
(IPC1-7): A61F2/48; G09B19/00

**- European:** A61F5/01D; B25J9/16K; B25J13/08V; B25J19/00B

**Application number:** US19910648733 19910131

**Priority number(s):** US19910648733 19910131

**Also published as:**

- WO9213504 (A1)
- JP6505407 (T)
- ES2074877 (T3)
- EP0569489 (A1)
- EP0569489 (B1)

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**Cited documents:**

- US4078670 (A)
- US4237873 (A)
- US4760850 (A)
- US5020790 (A)
- EP0380060 (A2)

### Abstract of US 5201772 (A)

A six degree of freedom limb movement resistance system is described in which a linkage system of links and joints couples a fixed point in space to a movable end-point of the linkage. A limb coupling cuff is attached to the end point. Variable resistance force can be applied to the linkage via computer controls through a feedback path from position and velocity sensors. The linkage endpoint force acting to resist limb motion is in a direction opposite to the endpoint velocity vector.

